

Mathematics and Statistics College of Arts and Sciences

Software Compatibility Testing

Consider the following problem: Assume we have downloaded 7 new programs to our computer. We have enough memory to run at most 3 of them at a time. What is the most efficient way to test if each pair of programs is pairwise compatible with each other? Assume the simultaneous operation of any k programs $(k \leq 3)$ takes 1 minute?

Possible solutions:

Test every 3 element subset: $\binom{7}{3} = 35$ minutes Test each pair of programs: $\binom{7}{2} = 21$ minutes

These solutions are wasteful, as they test the same sets of programs multiple times. Can a waste-free scheme be constructed?

Block Designs

A block design (S, B), or simply B, consists of a set S of v vertices and a collection B of b non-empty subsets of S. If in a design, each block consists of k vertices, then the design is called uniform or k-uniform.

A block design is called incomplete if there exists a block in B that does not contain all vertices of S; otherwise it is complete. If each vertex of a design occurs in exactly r blocks, then the design is called regular or *r*-regular.

$$\begin{array}{l} \{A,B\}\\ \{A,C\}\\ \{B,D\}\\ \{B,D\}\\ \{B,D\}\\ \{C,D\} \end{array} \end{array}$$

B has k = 2 vertices in each block, and each vertex occurs in r = 3 blocks.

Block Designs

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Balanced Incomplete Block Designs

If in a k-uniform, r-regular incomplete design (S, B), each pair of vertices occurs together in exactly λ blocks, we say that (S, B) is a balanced incomplete block design, or BIBD, of parameters $(b, v, r, k, \lambda).$

The computer program problem from the Introduction section can be modelled by the following BIBD of parameters (7, 7, 3, 3, 1), where each program corresponds to one of the vertices in $S = \{A, B, C, D, E, F, G\}$:

- Each program is tested with each other one exactly $\lambda = 1$ time.
- The block size is k = 3

A block design can be represented by an incidence matrix A that has v rows that correspond to each of the vertices and b columns that correspond to each block of the design.

An entry a_{ij} can assume a value of 0 or 1: 1 if the vertex iappears in the block *j*, otherwise 0.

		B_1	B_2	B_3	B_4	B_5	B_6	B_7
	\boldsymbol{A}	[1	0	1	1	0	0	0]
	B	1	1	0	0	1	0	0
	C	0	1	1	0	0	1	0
A =	D	1	0	0	0	0	1	1
	E	0	1	0	1	0	0	1
	F	0	0	1	0	1	0	1
	G	0	0	0	1	1	1	$\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 1 \\ 1 \\ 0 \end{bmatrix}$
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<u>Theorem (Fisher's Inequality)</u>: if a BIBD exists, then $b \ge v$, that is, every BIBD has at least as many blocks as it has vertices.

<u>Proof idea:</u> Let A be the incidence matrix of a BIBD. Richard Brualdi proves that the determinant of A times its transpose $AA^{T} = (r - \lambda)^{\nu-1}(r + (\nu - 1)\lambda)$. Since $\lambda < r$, this determinant is nonzero. Thus, AA^{T} is invertible. This implies the rank of AA^{T} is equal to v. So, the rank of A is at least v, and since A is a v-by-b matrix, we have $b \geq v$.

$$\{ \mathbf{A}, B, D \}$$
$$\{ \mathbf{B}, \mathbf{C}, \mathbf{E} \}$$
$$\{ \mathbf{A}, F, C \}$$
$$\{ \mathbf{A}, F, C \}$$
$$\{ \mathbf{A}, E, G \}$$
$$\{ B, F, G \}$$
$$\{ C, D, G \}$$
$$\{ D, \mathbf{E}, \mathbf{F} \}$$

Balanced block designs with block size k = 3 are called <u>Steiner</u> triple systems.

Steiner triple systems are extremely powerful; they can be constructed easily if v and λ are known:

$$r = \frac{\lambda(\nu - 1)}{2}$$

A Steiner triple system with k fixed at 1 is known as a Kirkman triple system.

Kirkman triple systems were made famous by the following problem posed by Thomas Kirkman in *The Lady's and* Gentleman's Diary, a British mathematical journal from the 1850s:

VI. QUERY; by the Rev. THOS. P. KIRKMAN, Croft, near Warrington. Fifteen young ladies in a school walk out three abreast for seven days in succession: it is required to arrange them daily, so that no two shall walk twice abreast.

A Kirkman triple system can easily be constructed to solve this problem with r = 7 and v = 15:

$\{ \begin{array}{c} 0, 1, 2 \\ \{ 3, 7, 11 \} \\ \{ 4, 9, 14 \} \\ \{ 5, 10, 12 \} \\ \{ 6, 8, 13 \} \end{array}$	$\{0, 3, 4\} \\ \{1, 7, 9\} \\ \{2, 12, 13\} \\ \{5, 8, 14\} \\ \{6, 10, 11\}$	$\{0, 5, 6\} \\ \{1, 8, 10\} \\ \{2, 11, 14\} \\ \{3, 9, 13\} \\ \{4, 7, 12\}$	$\{0, 7, 8\} \\ \{1, 11, 13\} \\ \{2, 4, 5\} \\ \{3, 10, 14\} \\ \{6, 9, 12\}$
$\{0, 9, 10\} \\ \{1, 12, 14\} \\ \{2, 3, 6\} \\ \{4, 8, 11\} \\ \{5, 7, 13\}$	$\{0, 11, 12\} \\ \{1, 3, 5\} \\ \{2, 8, 9\} \\ \{4, 10, 13\} \\ \{6, 7, 10\}$	$\{ \begin{array}{c} \{0,13,14\} \\ \{ \begin{array}{c} 1,4,6 \} \\ \{2,7,10\} \\ \{3,8,12\} \\ \{5,9,11\} \end{array} \}$	

References

- Pearson/Prentice Hall, 2004.
- *Diary*, 1846-1850:48.

Triple Systems

$$b = \frac{\lambda v(v-1)}{6}$$

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